

## Experiment No : M8

### Experiment Name: Steiner's theorem (parallel axis theorem)

#### Objective:

1. Determining the moment of inertia of a circular disk for various distances between the axis of rotation and the axis of symmetry.
2. Confirming Steiner's theorem (parallel axis theorem).

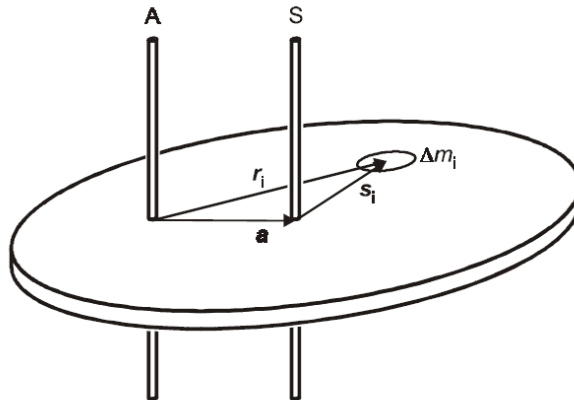
**Keywords:** Rotational motions, moment of inertia, parallel axis theorem, oscillation, period.

#### Theoretical Background:

The moment of inertia of an arbitrary rigid body whose mass elements  $\Delta m_i$  have the distances  $r_i$  from the axis of rotation A is

$$I^A = \sum_i \Delta m_i r_i^2 \quad 8.1$$

If the axis of rotation *does not* pass through the centre of mass (CM) of the body, application of Eq. 8.1 leads to an involved calculation. Often it is easier to calculate the moment of inertia  $I_{CM}$  with respect to the axis S, which is parallel to the axis of rotation (A) and passes through the centre of mass of the body.



**Figure 8.1:** Schematic illustration referring to the derivation of Steiner's theorem (parallel axis theorem)

For deriving the relation between  $I^A$  and  $I_{CM}$ , the plane perpendicular to the axis of rotation where the respective mass element  $\Delta m_i$  is located is considered (see Fig. 8.1). In this plane, the vector  $\mathbf{a}$  points from the axis of rotation to the centre-of-mass axis, the vector  $\mathbf{r}_i$  points from the axis of rotation to the mass element  $\Delta m_i$ , and the vector  $\mathbf{s}_i$  points from the centre-of-mass axis to the mass element. Thus

$$r_i = a + s_i \quad 8.2$$

and the squares of the distances in Eq. 8.1 are

$$r_i^2 = (a + s_i)^2 = a^2 + 2 \cdot a \cdot s_i + s_i^2 \quad 8.3$$

Therefore the sum in Eq.8.1 can be split into three terms:

$$I = \left( \sum_i \Delta m_i \right) a^2 + 2 \left( \sum_i \Delta m_i s_i \right) a + \sum_i \Delta m_i s_i^2 \quad 8.4$$

In the first summand,

$$\sum_i \Delta m_i = M \quad 8.5$$

is the total mass of the body. In the last summand,

$$\sum_i \Delta m_i s_i^2 = I_{CM} \quad 8.6$$

is the moment of inertia of the body with respect to the centre-of-mass axis. In the middle summand,

$$\sum_i \Delta m_i s_i^2 = 0 \quad 8.7$$

because the vectors  $s_i$  start from the axis through the centre of mass.

Thus Steiner's theorem follows from Eq. 8.4:

$$I^A = Ma^2 + I_{CM} \quad 8.8$$

This theorem will be verified in the experiment with a flat circular disk as an example. Its moment of inertia  $I^A$  with respect to an axis of rotation at a distance  $a$  from the axis of symmetry is obtained from the period of oscillation  $T$  of a torsion axle to which the circular disk is attached. We have

$$I^A = D \left( \frac{T}{2\pi} \right)^2 \quad 8.9$$

where  $D$  is restoring torque of the torsion axle.